



TECNOSPIRO MACHINE TOOL, S.L.U.

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1 ABOUT THIS MANUAL

This is the instruction manual for the ROSCAMAT[®] MOSQUITO tapping machine.

- ORIGINAL MANUAL-

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1.1 <u>CONSIDERATIONS</u>

- ✓ Before using the equipment, make sure you read this instruction manual and follow the safety and operating instructions fully.
- ✓ All the instructions contained in this manual refer to the individual device; the end user is responsible for analysing and applying all the necessary safety measures required for the intended use.

- ✓ This manual must be kept near the device for consultation throughout its working life.
- ✓ If any part of this manual seems unclear, confusing or imprecise, please do not hesitate to contact your 3arm[®] and/or Roscamat[®] distributor.
- ✓ The contents of this manual may be subject to change without prior notice.
- ✓ If the manual is lost or damaged, contact TECNOSPIRO MACHINE TOOL, S.L.U. so we can provide you with a new one.
- This document, or any part thereof, may only be reproduced or provided to third parties with the express written authorisation of TECNOSPIRO MACHINE TOOL, S.L.U.
- Some details of the illustrations in this manual may differ from the specific device configuration. They should be understood as representative of the standard product.

Paragraphs indicating assembly, adjustment, installation and maintenance steps are indicated by brown shading.

Paragraphs containing important information are indicated by grey shading.

1.2 <u>VERSION</u>

Document	Revision date
Instruction Manual	2/16/2024

2 <u>SAFETY INFORMATION</u>

2.1 <u>SCOPE OF APPLICATION</u>

This section contains extremely important information on the safe operation of the device and is intended for anyone involved in any stage of the life cycle of this device (transport, assembly and installation, commissioning, adjustment–training, operation, cleaning, maintenance, troubleshooting and disassembly/ decommissioning).

2.2 <u>WARNINGS AND GENERAL</u> <u>CONSIDERATIONS</u>

- ✓ The device described in this document has been built using current technology and in accordance with applicable technical standards on safety. However, misuse or improper set-up by the end user may result in a risk of injury.
- The device must only be used if it is proper working order, and all safety rules and instructions in this document must be obeyed.
- Any problem that could affect the safety of the device must be corrected immediately.
- ✓ No modifications must be made to the device without due authorisation from TECNOSPIRO MACHINE TOOL, S.L.U.
- ✓ The device must only be used for the intended purpose; any other use is strictly prohibited. All use other than that

indicated here will be considered misuse and is prohibited. The manufacturer assumes no liability for damage that may result from such misuse.

- ✓ The installer, owner and/or end user are responsible for determining whether the product is appropriate for each specific use, as well as determining the installation site and concretely defining the task to be performed with this product, within the limits set forth in this manual.
- ✓ Do not use it for any purpose not covered in this manual.
- ✓ The operator may only operate the device after having received applicable instructions for its use.
- It is recommended that only one operator use the device at one time; any other use must be evaluated by the installer / end user.
- Manipulating the device's moving parts and joints whilst the device is in use is strictly prohibited.
- ✓ When the manipulator is not in use, it must be left in the folded, or parked, position.
- ✓ Working parts (parts for tapping) must be correctly secured.
 - ✓ Tapping materials must comply with the manufacturer's instructions.
 - ✓ The operator must only use the device to perform safe movements, moving together with the device at all times to reduce the risk of uncontrolled or

involuntary movement of the equipment.

- Even though the parts that present the greatest risk of possible shearing or pinching are protected and enclosed, moving and jointed parts must not be handled during use.
- ✓ The working area of the device and its closest area of influence must comply with conditions of workplace safety, health and hygiene; the installer / end user are responsible for conducting a study to ensure safety.
- ✓ The operator must remain outside the vertical path of the swing arm.
- ✓ The presence of others in the device's working area must be restricted as much as possible in order to avoid any risk to safety; if any other use is intended, a supplemental study of the risks arising from the working mode must be conducted.
- ✓ It is important for operators of this device to be familiar with and have sufficient training in the use of this product or similar equipment.
- In any event, the operator must read and understand this manual before using the device, regardless of their prior knowledge, training or experience with similar equipment; the sections on installation, operation and safety are especially critical.

✓ If unsure about device usage or maintenance procedures, please contact your 3arm[®] and/or Roscamat[®] distributor.

2.3 <u>EXCLUSIONS</u>

The device is not intended for the following uses:

- Manipulation of any components or functions of the device aside from those specified in this manual.
- ✓ Use by persons with any type of disability, or by animals
- ✓ Use by staff who have not completed occupational risk prevention training

Excluded installation sites:

- ✓ Installation in corrosive areas
- ✓ Installation in dusty areas
- ✓ Installation in areas with high electromagnetic emissions
- ✓ Installation in areas with extreme temperatures (very high or very low)
- ✓ Installation in areas with high humidity
- ✓ Outdoors installation

2.4 SYMBOLS AND ICONS

 Throughout this manual and on the structure of the machine itself, you may see various symbols and icons whose meaning is summarised below:

	Danger: General danger symbol. This symbol is generally accompanied by an additional symbol or a more detailed description of the danger.
	Risk of pinching
4	Electrical hazard

2.5 <u>SYSTEM INSTALLER</u>

The system installer or end user is responsible for installing the machinery in accordance with all applicable safety measures.

The installer / end user is responsible for the following tasks:

- ✓ Location and proper installation.
- ✓ Connections.
- ✓ Risk assessment.
- ✓ Installation of mandatory safety and protectives features.

2.6 <u>PERSONAL PROTECTIVE</u> <u>EQUIPMENT (PPE)</u>

The following personal protective equipment should be used with this machine: safety boots, hardhat, safety goggles and safety gloves for transport, assembly and installation, commissioning and dismantling.

Safety footwear, safety gloves and safety goggles for adjustment, training, operation and troubleshooting.

The installer or end user is responsible for specifying the required personal protective equipment for the intended application of the machinery and to meet essential health, safety and hygiene requirements.

Operators must not wear loose clothing, rings, bracelets or watches since these may become caught in the workings of the machinery.

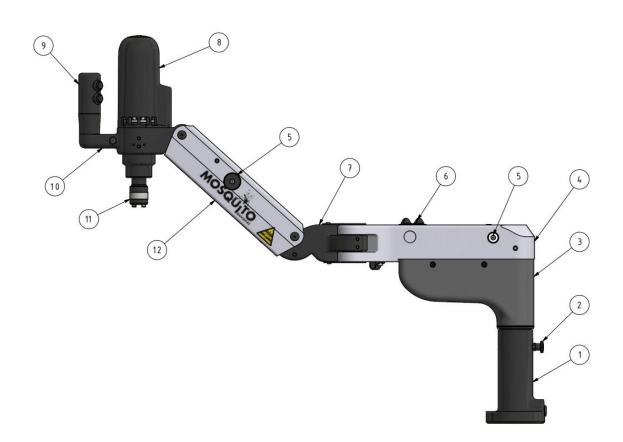
Hair must be tied up to prevent it getting caught in the moving parts of the machinery.

2.7 <u>LEVEL OF TRAINING FOR</u> <u>PERSONNEL WHO WORK WITH THE</u> <u>DEVICE</u>

Anyone who works with the machinery must have read and understood the information in the chapter on safety.

3 GENERAL DESCRIPTION AND TECHNICAL INFORMATION

3.1 MAIN PARTS



- 1.- Base
- 2.- Lift mechanism control
- 3.- Lift mechanism/electrical box cover
- 4.- Radial arm
- 5.- Arm lock (magnetic)
- 6.- Speed control

- 7.- Elbow joint assembly
- 8.- Electric motor
- 9.- Grip/motor control buttons
- 10.- Head assembly
- 11.- Quick-change clutch
- 12.- Articulated arm

3.2 DESCRIPTION AND OPERATING PRINCIPLES

The machine comprises a combined base and column attached to a radial arm, a swing arm balanced by a gas spring, and a head assembly. These components provide the mounting for the motor and ensure that it is positioned perpendicular to the working area. The operator uses the motor grip to align the head assembly with the part requiring tapping.

The equipment has a high-frequency motor, controlled by a frequency variator inside the electronic component housing. The turning speed of the motor (to the left and to the right) and automatic lubrication (optional) can be controlled using the turning speed adjustment.

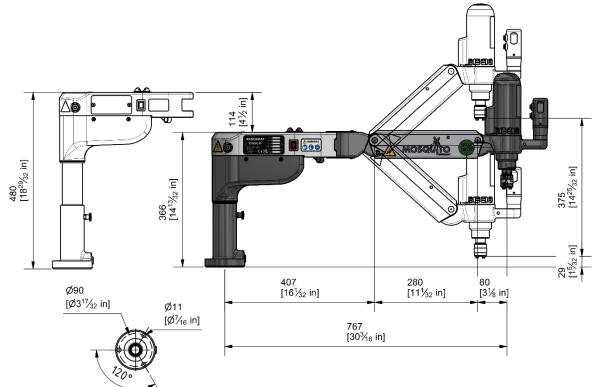
The tool holder (or tap holder), with or without safety clutch, is also connected to the motor by means of a quick-change system.

3.3 <u>CONFIGURATIONS</u>

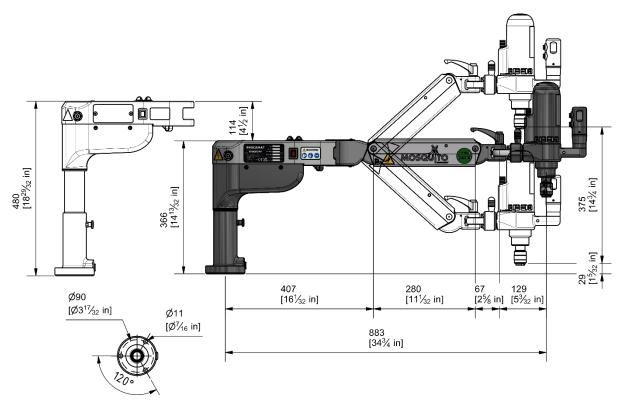
The following machine configurations are available (in both 120-V and 230-V versions):

	ARTICULATED HEAD ASSEMBLY	HEAD ASSEMBLY VERTICAL	LUBRICATION	300 RPM	600 RPM	300/600 RPM
MOSQUITO V - 300 RPM		\checkmark		\checkmark		
MOSQUITO V - 600 RPM		\checkmark			\checkmark	
MOSQUITO V 2V – 300/600 RPM		\checkmark				\checkmark
MOSQUITO VH - 300 RPM	\checkmark			\checkmark		
MOSQUITO VH - 600 RPM	\checkmark				\checkmark	
MOSQUITO VH 2V – 300/600 RPM	\checkmark					\checkmark
MOSQUITO V E - 300 RPM		\checkmark	\checkmark	\checkmark		
MOSQUITO V E - 600 RPM		\checkmark	\checkmark		\checkmark	
MOSQUITO V 2V E – 300/600 RPM		\checkmark	\checkmark			\checkmark
MOSQUITO VH E - 300 RPM	\checkmark		\checkmark	\checkmark		
MOSQUITO VH E - 600 RPM	\checkmark		\checkmark		\checkmark	
MOSQUITO VH 2V E – 300/600 RPM	\checkmark		\checkmark			\checkmark

3.4 **DIMENSIONS**



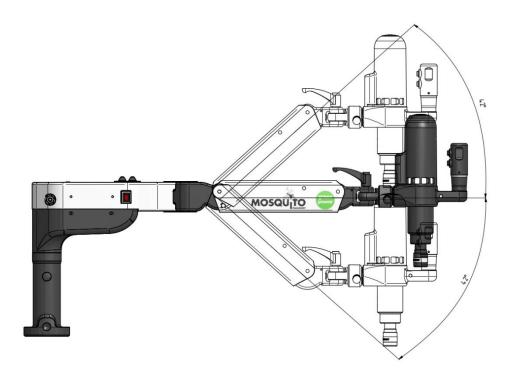
Roscamat MOSQUITO - Vertical head assembly



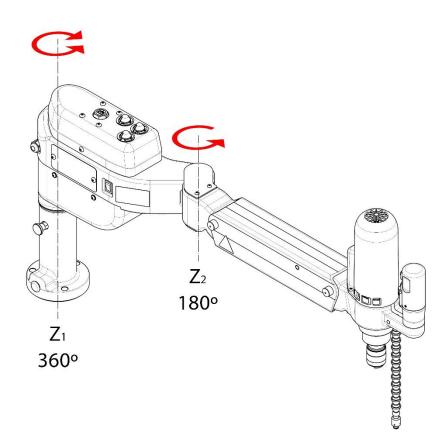
Roscamat MOSQUITO – Articulated head assembly

3.5 <u>MOVEMENTS</u>

3.5.1 <u>Vertical movements</u>



3.5.2 <u>Radial movements</u>



3.6 TECHNICAL SPECIFICATIONS

GENERAL TECHNICAL SPECIFICATIONS					
Tapping capacity ¹		M2-M14			
Suitable materials for tapping ²		Metals and metal and			
		plastic materials			
Speed		300 rpm			
		600 rpm			
		300/600 rpm			
Empty weight		15 kg <i>(33 lb)</i>			
Electrical specifications					
	Power supply voltage and frequency	220–240 V 50 Hz			
	Motor power	0.45 kW			
	Protection class	IP 54			
	Power supply voltage and frequency	100–120 V 60 Hz			
	Motor power	0.45 kW			
	Protection class	IP 54			
Working conditions					
	Temperature	10 °C a +50 °C <i>(14–122 °F)</i>			
	Relative humidity	Max. 70%			
	Environment	Industrial environments			

3.7 IDENTIFICATION PLATE

A metal plate on the radial arm of the machine provides details of the following:

Manufacturer (name, address and company name), manufacture date, serial number, model, power supply voltage and frequency, motor power and CE and UKCA mark.



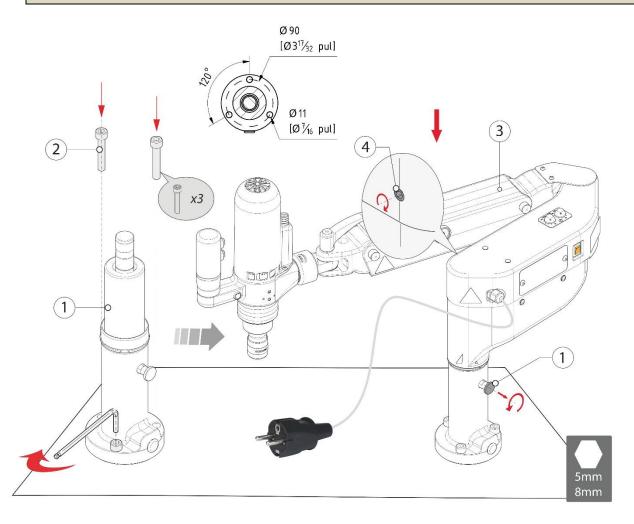
¹ Minimum and maximum tapping values for tapping with 90 kg/mm² steel.

² In general, all types of metals and plastics can be used. Special care must be taken with materials such as magnesium (highly flammable) and certain plastics. Any other type of material must be subject to an additional study to identify risks by the installer or end user.

4 INSTALLATION, ADJUSTMENTS AND OPERATION

4.1 <u>INSTALLATION</u>

- 1. Remove the equipment from the original packing.
- 2. Anchor the base (1) using 3 M10 bolts (2) (Recommended torque 45Nm) suited to the chosen installation site (alternative methods may be used if approved by the installer).
- 3. Mount the machine (3) on the spindle of the base (1) and firmly tighten the stud (4) *(5-mm Allen key).*
- 4. Connect the power supply.



The installation site must be horizontal to prevent drifting or shifting.



INSTALLATION SITE

Do not install the device in areas such as:

- ✓ Explosion or fire hazard zones.
- ✓ Outdoor areas.
- ✓ Areas with corrosive atmospheres.
- ✓ Areas with extreme temperatures (very high or very low).
- ✓ Areas with high humidity.
- ✓ Dusty areas.
- ✓ Areas with high electromagnetic emissions.

4.2 ADJUSTMENTS

4.2.1 ADJUSTING MOTOR TURNING SPEED

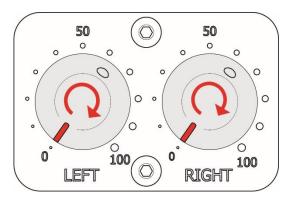
The motor turning speed can be adjusted using the dials on the electronic component housing.

To increase or decrease the tapping speed (clockwise direction):

- 1- Turn the dial marked RIGHT to the left or right as required.
- 2- A value of 50 indicates 50% of rated speed.

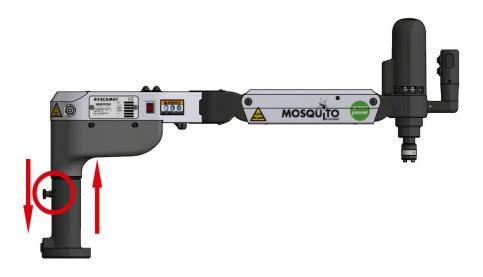
To increase or decrease the tap release speed (anti-clockwise direction):

- 3- Turn the dial marked LEFT to the left or right as required.
- 4- A value of 50 indicates 50% of rated speed.



4.2.2 ADJUSTING THE BASE HEIGHT

The machine can be raised 130 mm, allowing the operator to work at different heights. Follow the steps below:



Raising the arm:

- 1. Set the machine to the folded or parking position.
- 2. Raise the machine assembly as far as it will go.

Lowering the arm:

- 1. Set the machine to the folded or parking position.
- 2. Pull the lift control out and lower the assembly. Do not allow the machine to descend under its own weight. Support the assembly to stop it descending abruptly.



PLEASE NOTE

- C Do not allow the machine to descend under its own weight. Support the assembly to stop it descending abruptly.
- ✓ Do not place your hands below the bottom of the cover.

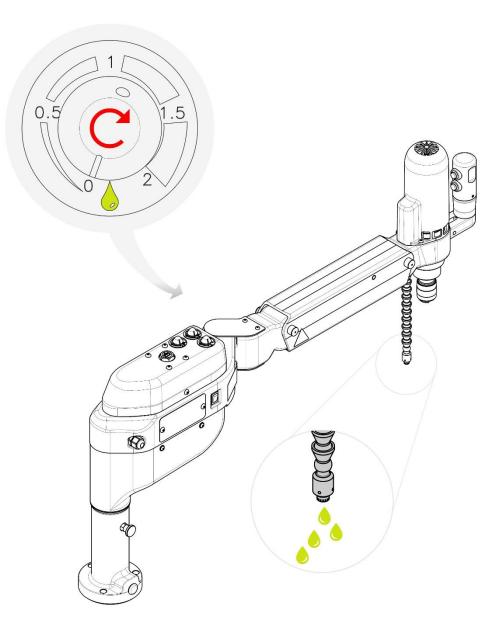
4.3 <u>LUBRICATION</u>

The oil pump and, therefore, the oil supply are activated simultaneously when the buttons that control the motor are pressed.

The lubrication time is counted in seconds and is adjusted using the potentiometer on the cover of the radial arm.

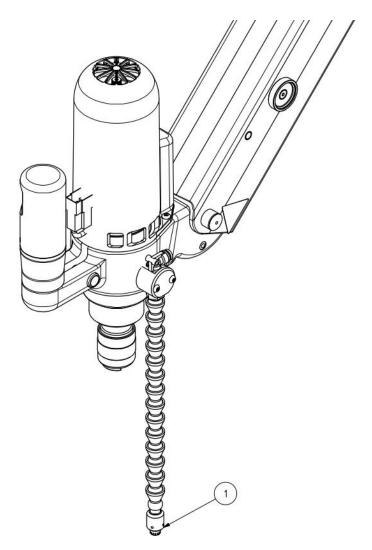
Lubrication time is adjusted as follows:

- 1. To increase the lubrication time, twist the potentiometer clockwise.
- 2. To decrease the lubrication time, twist the potentiometer anti-clockwise.



If the tank is empty, the pipes may fill with air. In this case, they must be bled after the tank is refilled.

- 1. Loosen the end (1) by rotating it 2 turns anticlockwise.
- 2. Increase the lubrication time to maximum and turn the motor several times until the pipes have been bled.
- 3. Tighten the end (1) by rotating it 2 turns clockwise.



The tank filler cap is located on top of the radial arm.

OIL SPECIFICATIONS

- ✓ Oil type: Viscosity of 20–40 cSt; EP (extreme pressure) additives (sulphur, phosphorus and inactive chlorides).
- ✓ ONLY USE PURE CUTTING OIL WITHOUT SOLVENTS. Certain types of tricolour or alcohol lubricants can seriously damage some system components.



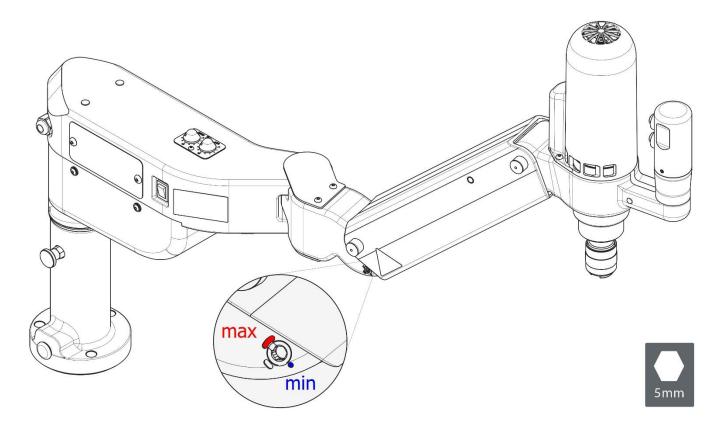
MAINTENANCE

Clean the oil tank regularly to remove metal shavings.

4.4 BALANCING THE ARM

Adjust the tension on the inner damper if the arm drops down or has too much upward force.

- 1- Keep the swing arm in an approximately horizontal position to facilitate operation.
- 2- Adjust the spring tension regulator as required (dot = minimum tension, dash = maximum tension).
- Turn anti-clockwise: reduce spring tension.
- Turn clockwise: increase spring tension.



5 OPERATION



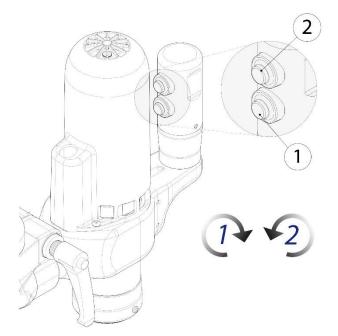
WARNING

- ✓ The sequence described below is for information purposes only and assumes that installation, adjustment (e.g. balancing and installing the arm) and configuration (e.g gears, where applicable, tap holder, with or without clutch, and tap) have been completed.
- ✓ Use the required personal protective equipment described in [see PERSONAL PROTECTIVE EQUIPMENT (PPE) p. -7-].
- ✓ Ensure the machine configuration is suitable for the characteristics of the tapping operation.
- Ensure the necessary adjustments have been made to adapt the equipment to the characteristics of the work to be carried out.
- Ensure the materials for tapping meet the requirements described in [See TECHNICAL SPECIFICATIONS p. -12-].
- \checkmark The parts to be worked must be secured correctly.
- ✓ Upon completion of the task or during periods of prolonged inactivity, set the machine to folded or parking position.

5.1 <u>TAPPING</u>

Follow the steps below for a correct and safe sequence for the tapping operation.

- 1- Switch on the main switch.
- 2- To perform tapping (clockwise rotation), hold down button³ 1.
- 3- Hold button 2 to release the tap (turning to the left).
- 4- Move the machine to its folded or parking condition and switch off at the main switch.



³ Holding down buttons 1 and 2 prevents the machine operating without the intervention/supervision of an operator.

The machine incorporates a screen with a cycle counter.

0000000

When you turn on the equipment, appears the total cycle counter.

Once you start to work, on the screen will appear a partial counter during the working session.

To view the total counter, you have to turn off the equipment, wait for 5 seconds and turn on the equipment again.

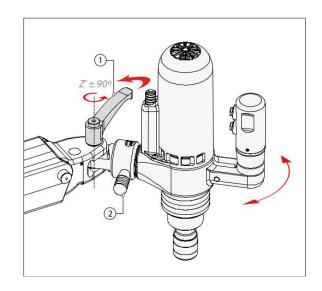
6 HEAD ASSEMBLIES

6.1 ARTICULATED HEAD ASSEMBLY

The articulated head assembly allows the motor to be used in 4 positions (at 90° intervals) to perform both vertical and horizontal tapping.

Vertical operations:

1- Align the motor vertically and firmly tighten the handle (1) and handwheel (2) as far as they allow.



Horizontal operations:

- 1- Release the handwheel (2) to loosen the motor join.
- 2- Rotate the head assembly 90° until it locks and firmly re-tighten the handwheel (2).
- 3- Release the handle (1) on the upper part of the head assembly.
- 4- When moving the arm, the operator must manually ensure it is perpendicular to the reference plane.



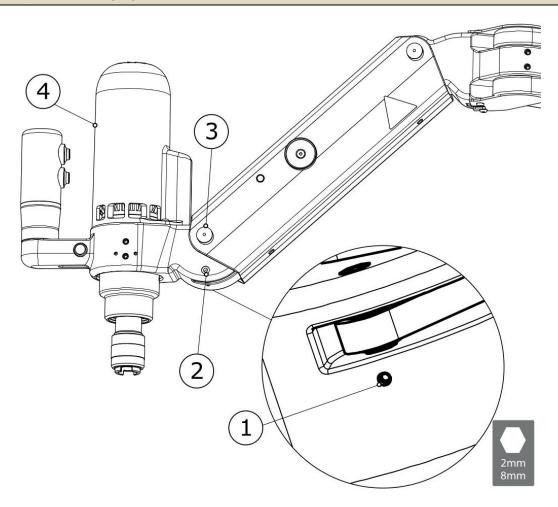
- Do not block the handle (1) for horizontal operation.
- The handle (2) can only be locked in the 4 right-angle positions.

7 <u>MAINTENANCE</u>

7.1 <u>REPLACING THE GAS SPRING</u>

BEFORE REPLACING THE GAS SPRING

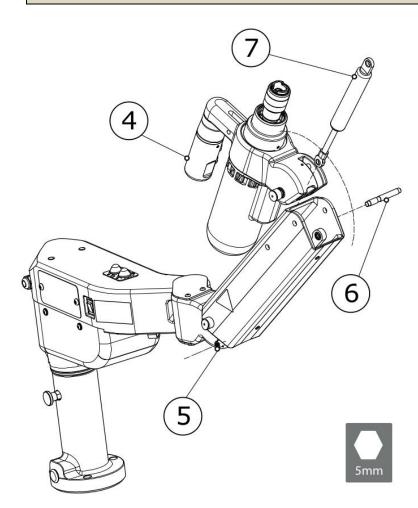
- ✓ The equipment must be correctly installed and set-up.
- \checkmark Switch off the equipment at the main switch and disconnect from the power supply.
- \checkmark If necessary, assign two operators to this operation to ensure it is performed safely.
 - 1- Lower the arm to its lowest position and remove the stud (1) (2-mm Allen key).
 - 2- Using an M5 extractor, remove the spindle (2).
 - 3- Remove the plugs and bolts (3) (8-mm Allen key). Note that the head assembly (4) will be suspended solely by the cables.

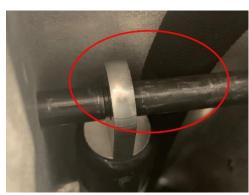


PLEASE NOTE

Always keep the arm in its highest position.

- 4- Loosen the cam (5) (5-mm Allen key) to reduce the tension in the damper.
- 5- Remove the pin (6) from the arm and remove the cam (5).
- 6- Remove the damper (7) and replace it with a new one.
- 7- Mount the cam (5) on the shaft of the new damper and make sure that it is securely in place.
- 8- When inserting the pin (6), make sure the head assembly cables pass over it.
- 9- Attach the head assembly and tighten the bolts (3).
- 10-Position the spindle (2) with the slot facing downwards and re-insert the stud (1).





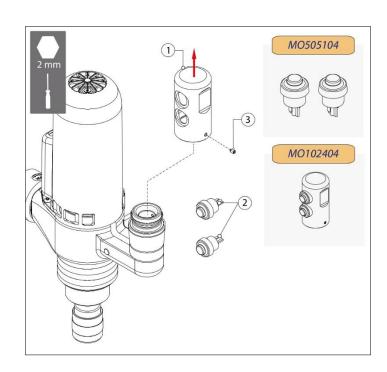
Machine/model	Reference	Machine/model V-H	Reference
Roscamat Mosquito 300 rpm -400N-	MO1021A3	Roscamat Mosquito V-H 300 rpm -450N-	MO1027A3
Roscamat Mosquito 600 rpm -400N-	MO1021A3	Roscamat Mosquito V-H 600 rpm -450N-	MO1027A3
Roscamat Mosquito 2-speed -450N-	MO1027A3	Roscamat Mosquito V-H 2-speed -500N-	MO2005A3

7.2 REPLACING THE GRIP AND BUTTONS

BEFORE REPLACING THE GRIP

The equipment must be correctly installed and set-up.

- ✓ Switch off the equipment at the main switch and disconnect from the power supply.
 - 1- Set the machine to the folded or parking position.
 - 2- Switch off at the main switch and unplug from the power supply.
 - 3- Remove the motor control buttons (2) and disconnect them from their FASTON connector *(use a small screwdriver to lift out the buttons).*
 - 4- Remove the bolt (3) (2-mm Allen key) and slide the grip (1) upwards as show in the diagram.
 - 5- For assembly, follow the procedure in reverse, making sure none of the cables are trapped.



7.3 <u>REPLACING THE OIL PUMP</u>

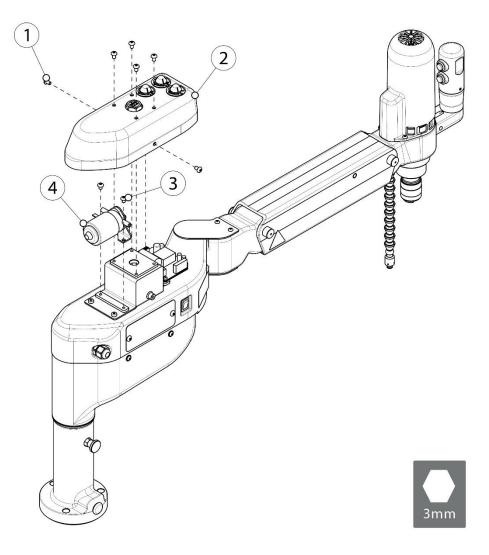


BEFORE REPLACING THE OIL PUMP

The equipment must be correctly installed and set-up.

✓ Switch off the equipment at the main switch and disconnect from the power supply.

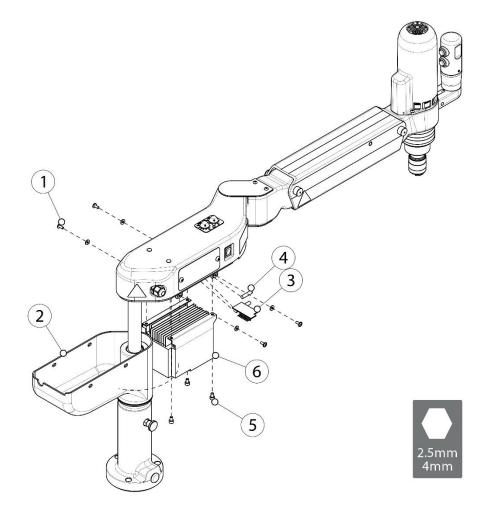
- 1. Raise the machine *[see* ADJUSTING THE BASE HEIGHT *p.15].*
- 2. Remove the 6 bolts (1) (3-mm Allen key) from the cover of the lubrication system (2) located on the radial arm and remove the cover.
- 3. Disconnect the two FASTON terminals and the oil pump inlet and outlet tubes.
- 4. Loosen the 2 bolts (3) (3-mm Allen key) that hold the oil pump (4) in place and replace the pump.
- 5. For assembly, follow the procedure in reverse.



7.4 REPLACING THE VARIABLE-SPEED DRIVE



- The equipment must be correctly installed and set-up
- Switch off the equipment at the main switch and disconnect from the power supply
 - 1. Raise the machine [see ADJUSTING THE BASE HEIGHT p. 15].
 - 2. Remove the 4 bolts (1) (2.5-mm Allen key) from the cover of the electrical box (2) located on the radial arm and remove the cover.
 - 3. Remove the top cover protecting the variator connections.
 - 4. Disconnect the variator connection board (3).
 - 5. Remove the variator side protection.
 - 6. Disconnect the remaining cables (4).
 - 7. Remove the 4 bolts (5) (4-mm Allen key) attaching the variable-speed drive (6) to the radial arm and remove the drive.
 - 8. Attach the new variable-speed drive and connect all the cables to their corresponding connections *[see* ELECTRICAL DIAGRAM *p. 31].*
 - 9. Finally, replace the radial arm cover.



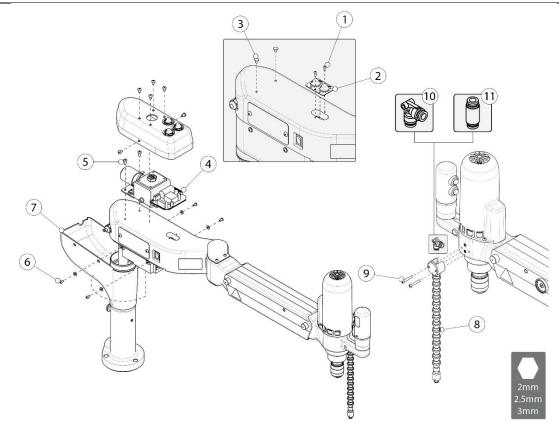
7.5 ASSEMBLY OF AUTOMATIC LUBRICATION KIT FOR THE TOOL

BEFORE ASSEMBLING THE AUTOMATIC LUBRICATION KIT

- The equipment must be correctly installed and set-up.
- Switch off the equipment at the main switch and disconnect from the power supply.
 - 1. Raise the machine *[see* ADJUSTING THE BASE HEIGHT *p.15].*
 - 2. Remove the 2 bolts (1) (2-mm Allen key) and remove the potentiometer (2).
 - 3. Remove the plugs (3).
 - 4. Attach the lubrication system assembly (4) using the bolts (5) (3-mm Allen key) provided.
 - 5. Remove the bolts (6) (2.5-mm Allen key) and remove the electrical box cover (7).
 - 6. Insert the fittings and connect the pump outlet pipe.
 - 7. Connect the potentiometer cable to the board supplied with the kit and the power and communications cables between the board and the variable-speed drive [see ELECTRICAL DIAGRAM p. 31].
 - 8. Connect the oil pipe to the lower part of the arm.
 - 9. Attach the articulated tube and nozzle (8) using the bolts (9) (2.5-mm Allen key) for the oil outlet (if working with a machine that only performs vertical tapping, attach fitting 10. If the machine performs both vertical and horizontal tapping, attach fitting 11).
 - 10. Fill the tank and make sure the filler cap is in place.

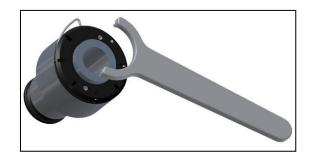
PLEASE NOTE

Before starting the system, the circuit must be bled [see LUBRICATION p. 16].



7.6 ADJUSTING THE CLUTCH

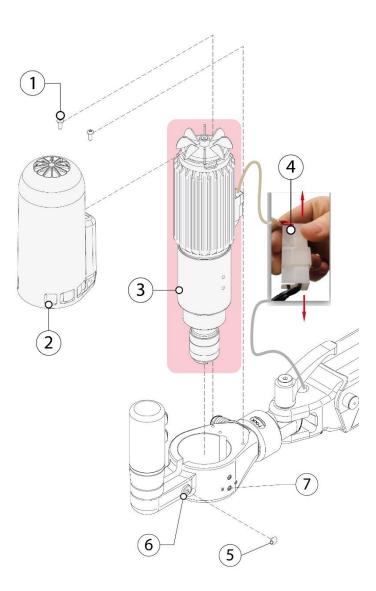
- 1. Remove the locking ring.
- 2. Turn the slotted nut clockwise to increase clutch tension and anticlockwise to decrease it.
- 3. Re-insert the ring in the slot.



7.7 REPLACING THE MOTOR (300 AND 600 RPM)

- 1- Set the machine to the folded or parking position.
- 2- Switch off at the main switch and unplug from the power supply.
- 3- Remove the bolts (1) (2.5-mm Allen key).
- 4- Slide the housing (2) up until the connector (4) is visible. Disconnect the connector as shown in the diagram and fully remove the housing (2).
- 5- Remove the plug (5) and loosen the bolt (6) (5-mm Allen key).
- 6- Loosen the studs (7) (3-mm Allen key).
- 7- Remove the motor (3) and replace if necessary.
- 8- Reverse the process for assembly.

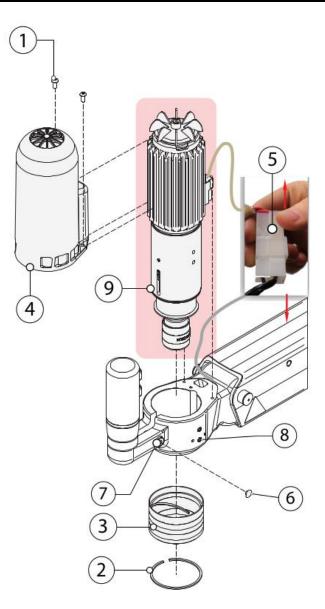
NOTE: When assembling the motor, make sure none of the cables are trapped.



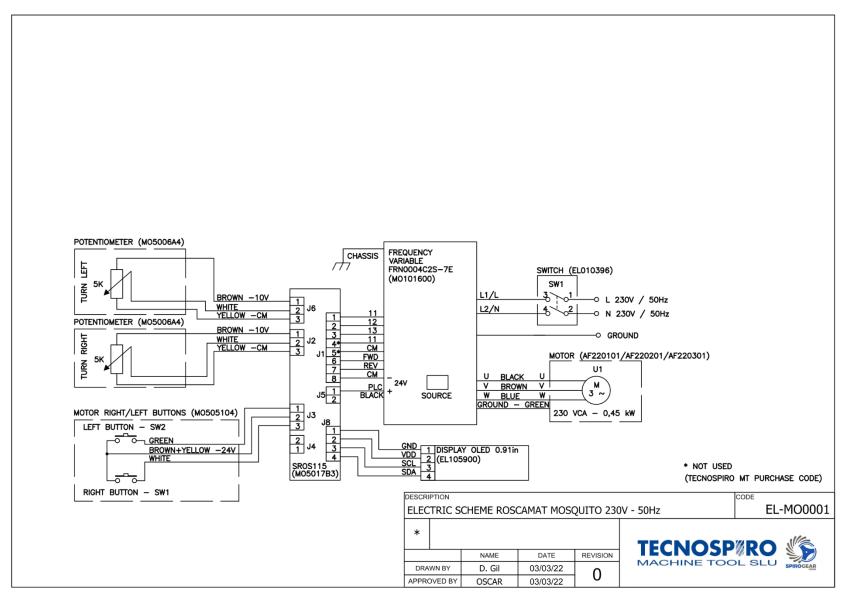
7.8 <u>REPLACING THE MOTOR (2 V)</u>

- 1- Set the machine to the folded or parking position.
- 2- Switch off at the main switch and unplug from the power supply.
- 3- Remove the Seeger ring (2) and remove the chuck (3).
- 4- Remove the bolts (1) (2.5-mm Allen key).
- 5- Slide the housing (4) up until the connector (5) is visible. Disconnect the connector as shown in the diagram and fully remove the housing (4).
- 6- Remove the plug (6) and loosen the bolt (7) (5-mm Allen key).
- 7- Loosen the studs (8) (3-mm Allen key).
- 8- Remove the motor (9) and replace if necessary.
- 9- Reverse the process for assembly.

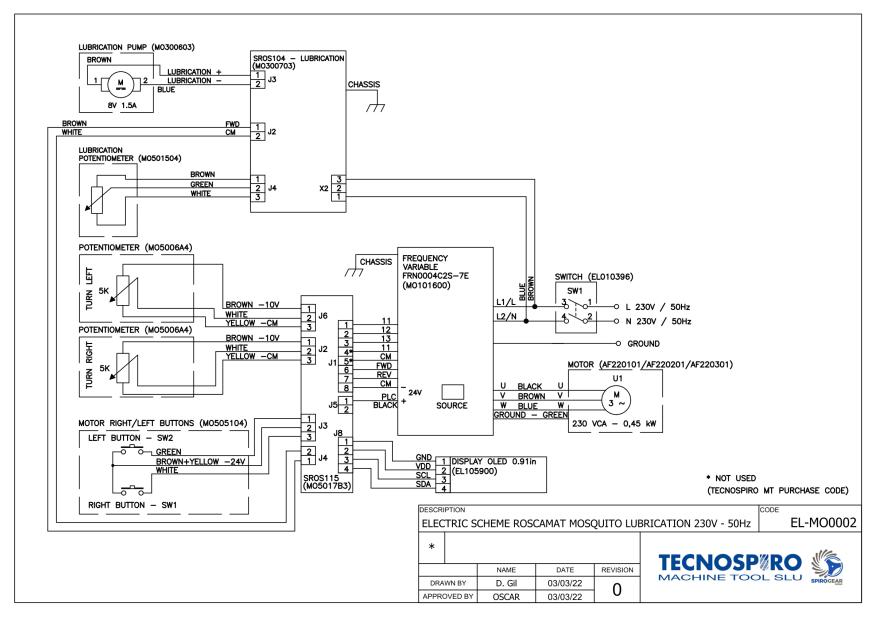
NOTE: When assembling the motor, make sure none of the cables are trapped.



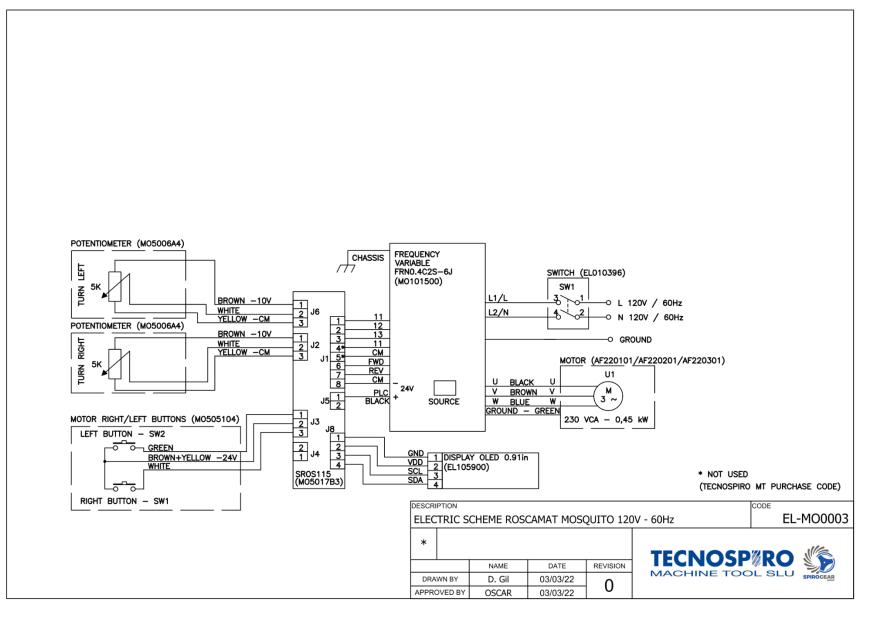
8 ELECTRICAL DIAGRAM



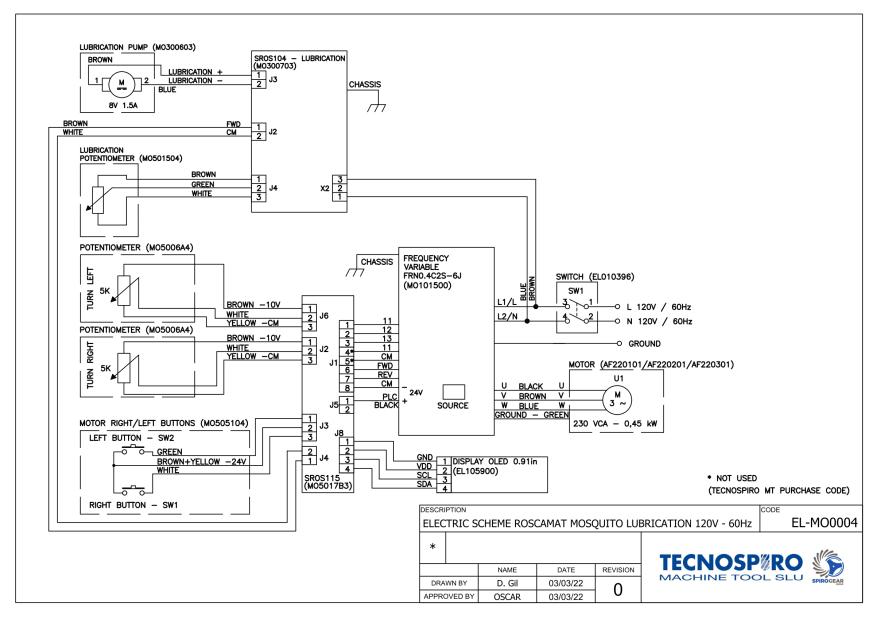
Electrical diagram, configurations WITHOUT lubrication – 230V



Electrical diagram, configurations WITH lubrication – 230V



Electrical diagram, configurations WITHOUT lubrication – 120V



Electrical diagram, configurations WITH lubrication – 120V

9 TROUBLESHOOTING

9.1 ISSUE: THE MACHINE DOES NOT WORK - THE MOTOR WILL NOT START OR HAS STOPPED

Remove the electrical box housing, leaving the electrical equipment uncovered and read the fault shown on the drive display.

Nominal dimensions			Technical Specifications		
	NO		Stop cause indicator		
			OC 1: Overcurrent during acceleration		
		Overcurrent protection	OC 2: Overcurrent during deceleration		
			OC 3: Overcurrent during operation at constant rpm		
		Network phase fault protection	L in: Entry phase fault		
		Insufficient voltage protection	LU: Insufficient voltage		
	0	Exit phase fault protection	OPL: Loss of output phase; problems in output cables of variator.		
	top	Overvoltage protection	OU1: Overvoltage during acceleration		
5	Emergency stop		OU2: Overvoltage during deceleration		
Indicator			OU3: Overvoltage during constant revolutions operation		
dic		Protection against	OH1: Excess temperature on heat sink; excess load or fault.		
lne		overheating	dbH: DB circuit overheating		
		External fault entry	OH2: External faults		
		Motor protection	OH4: Motor protection (PTC resistance)		
			OL1: Motor overload; electrothermal motor protection relay.		
		Overload protection	OLU: Variator overload		
			Er1: Memory fault		
			Er2: External control panel communications fault		
		Safety stop	Er3: CPU fault		
			Er6: Operational sequence fault		
			Er8: RS485 communications fault		
			ErF: Memorisation fault due to insufficient voltage		
	Operation, safety stop		Data from the last four faults are memorised and can be displayed.		
			Data stays memorised upon disconnecting the power		

In any event, the machine must be reset to restart process. Switch the machine off and wait about 25 seconds before turning on the equipment. If the problem is due to an external current or voltage fault, please wait until the current is stabilised. If the problem persists, contact your distributor or manufacturer.

9.2 ISSUE: TILTING ARM FALLS

Possible causes		Solution
1. Arm not balanced	=	Balance the arm according to the weight to be supported. [See BALANCING THE ARM page 18]
2 Defective damper	=	Replace it with a new one <i>[see REPLACING THE GAS SPRING p. 22]</i>

9.3 <u>PROBLEM: THE CLUTCH SLIPS AND THE TAP FAILS TO TURN WHILE THE MOTOR IS</u> <u>RUNNING</u>

Possible causes

- 1.- Clutch loose
- 2.- Insufficient tool lubrication
- 3.- Tap not suited to the material
- 4.- Tap in poor state (blunt)
- 5.- Hole misaligned
- 6.- Small hole diameter

Solution

- = Adjust the clutch *[see ADJUSTING THE CLUTCH p. 28].*
- = Use a suitable oil or emulsion for the material.
- = Use taps according to the material, following the manufacturer's instructions

9.4 PROBLEM: THE LUBRICATION SYSTEM DOES NOT WORK

Possible causes

- 1. Oil tank empty
- 2.- Grease stem blocked

Solution

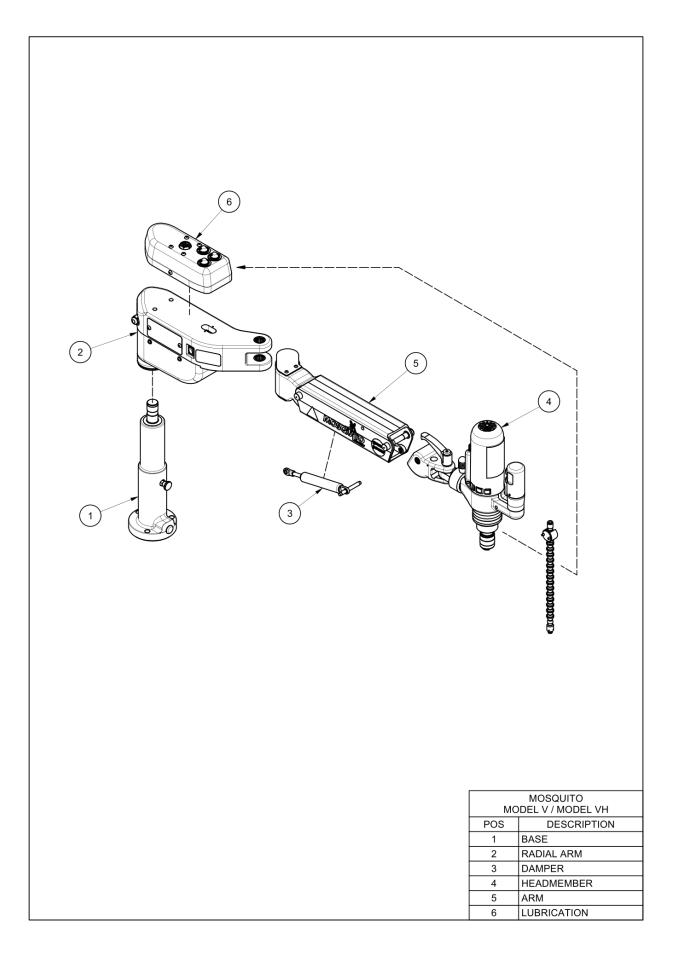
- = Fill tank [see LUBRICATION p. 16].
- Unscrew the end of the nozzle and clean it.
 (Please note: do not lose the spring and ball found inside the nozzle).

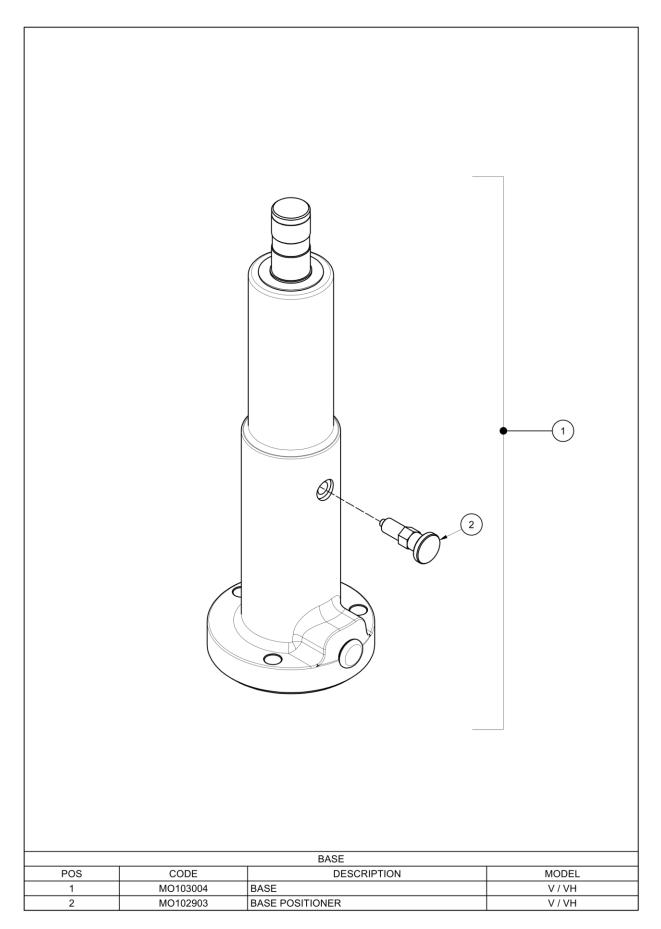
10 <u>WARRANTY</u>

See attached warranty document.

R@SCAMAT[®]

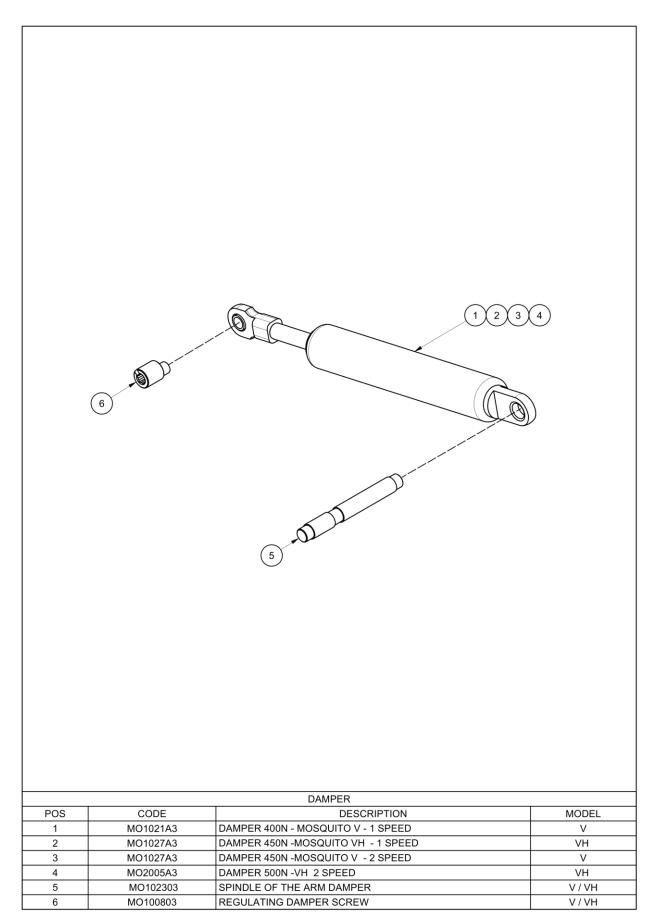
11 SPARE PARTS





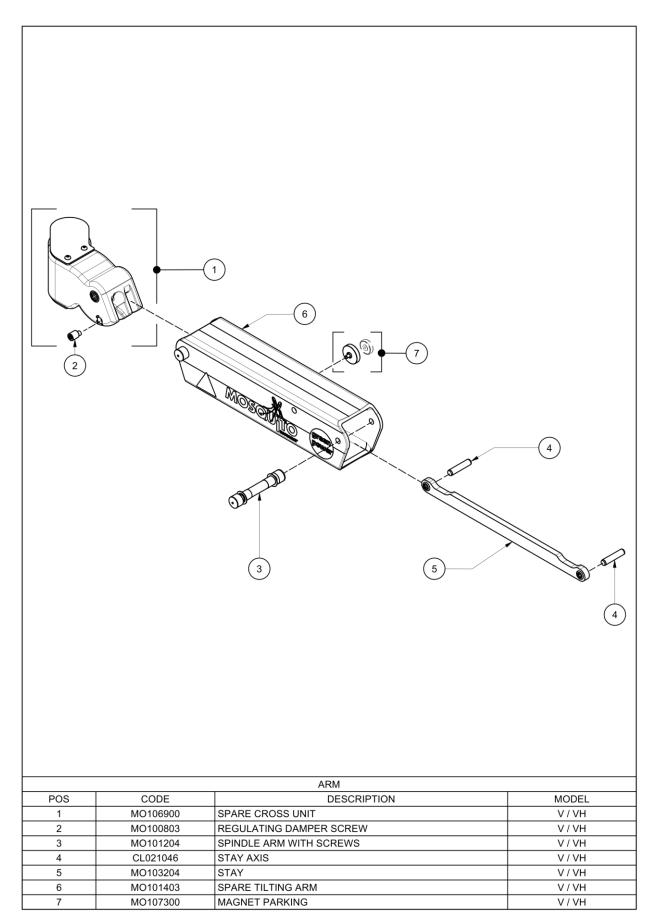
			-11	
		RADIAL ARM		
POS	CODE MO101600	DESCRIPTION ELECTRONIC EQUIPMENT - FREQUENCY VARIATOR BOARD (220V)	MODEL	
1 2	MO101600 MO101500R	ELECTRONIC EQUIPMENT - FREQUENCY VARIATOR BOARD (2200)	V / VH V / VH	
3	MO1019C3	BASE CASING		
4	EL010396	MAIN SWITCH	V / VH V / VH	
5	MO5017B3	ELECTRONIC BOARD OF CONNEXIONS	V / VH	
6	MO500504	PLUG WIRE	V / VH	
7	MO502204	MOTOR TO VARIATOR WIRE V		
8	MO500104	MOTOR TO VARIATOR WIRE VH		
9	MO5002A4	GRIP TO VARIATOR WIRE	VH	
10	MO502104	GRIP TO VARIATOR WIRE	V	
11	MO4003A4	2 SPEEDS POTENTIOMETER + WIRE	V / VH	
12	MO107000	SPARE RADIAL ARM	V / VH	
12	MO107000 MO107100	SPARE DISPLAY THREAD COUNTER	V / VH	
13				

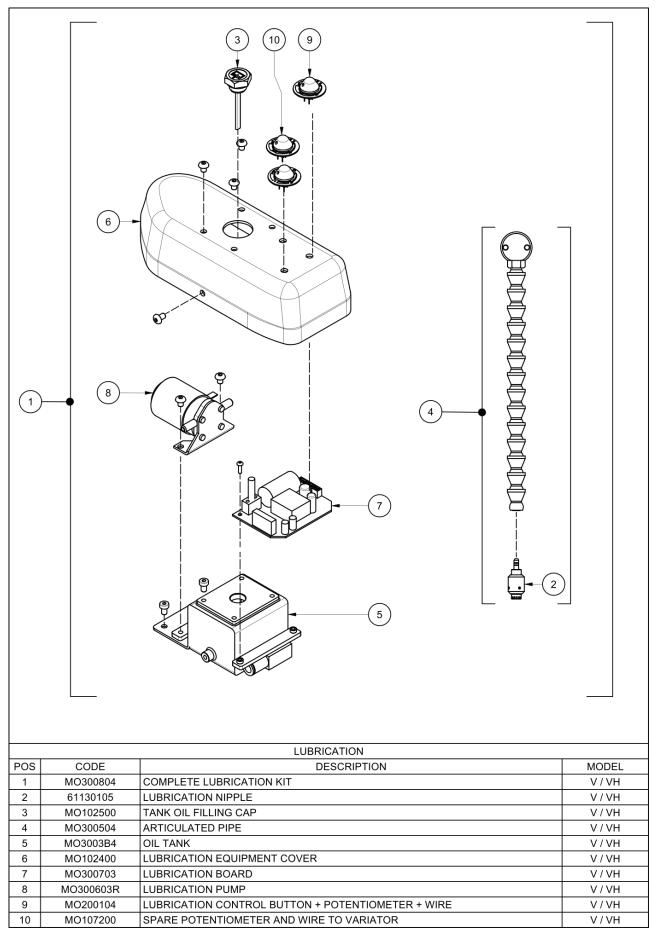
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• <u>10</u>
HEADMEMEBER
POS CODE DESCRIPTION MODEL
1 AF220101R HIGH FREQUENCY ELECTRIC MOTOR -MODEL TS-XI - 2 SPEEDS V / VH
2 AF220201R HIGH FREQUENCY ELECTRIC MOTOR -MODEL TS-XII - 600 RPM V / VH
3 AF220301R HIGH FREQUENCY ELECTRIC MOTOR -MODEL TS-XII - 300 RPM V / VH
4 AF211003 COOLING FAN V / VH
5 AC090036 QUICK CHANGE 19/1 V / VH
6 MO102404R MOTOR GRIP V / VH
7 MO505104 PUSH BUTTON KIT 2 UNIT V / VH
8 AF2101A3 MOTOR FRAMEWORK VH
9 AF211203 MOTOR FRAMEWORK V
10 MO200304 ORIENTABLE HEADMEMBER VH
11 MO103604 VERTICAL HEADMEMEBER V
12 MO200805 1/2 ORIENTABLE HEADMEMBER (MOTOR SUPPORT + TURNING BASE) VH
13 AC060546 HANDLE FOR ORIENTABLE HEADMEMBER VH
14 TG108100 MOTOR BALL BEARING - TOP COVER 6000 ZZ V / VH
15 MO106700 MOTOR BALL BEARING - LOWER COVER 6001 ZZ V / VH
16 AF211204 BODY ROTOR AF2 V / VH





12 GUIDELINES FOR PACKAGING, TRANSPORT AND DISASSEMBLY

12.1 <u>PACKAGING</u>

Follow the instructions below for packaging the device to change location or to ship it for repair and maintenance.

12.1.1 <u>Preparations</u>

The device must be taken out of service. Using straps during transport will prevent movement and possible damage to the equipment.

12.1.2 Choice of packaging

During long-distance transport, the device's component parts must be packaged appropriately to protect them against weather damage.

12.1.3 Inscription on packaging

Follow the specific provisions of the country where transport is taking place. For completely closed packages, a label must be placed on the package indicating which end is up.

12.1.4 Packing procedure

Place the device on manufactured wooden pallets. Using tie-down straps, secure the components to keep them from falling. Attach all accompanying technical documentation required for the device.

12.2 <u>TRANSPORT</u>

The following information must be considered when transporting the device. External dimensions according to segment (755 mm x 410 mm x 285 mm), approx. Total weight (according to segment): 16.5 kg.

12.3 DISASSEMBLY

- ✓ The equipment must be taken out of service by properly trained and authorised personnel.
- The equipment must be disassembled taking into account the instructions on safety, waste disposal and recycling.
- Protect the environment. The equipment must be disposed of following standards and directives in force in the areas of safety, noise prevention, environmental protection and accident prevention.



NOTES

DATE	DESCRIPTION

CE DECLARATION OF CONFORMITY

The manufacturer:

Company: TECNOSPIRO MACHINE TOOL, S.L.U. Address: P.I. Pla dels Vinyats I, s/n nau 1 City: Sant Joan de Vilatorrada - 08250 Spain - EU County: Declares that this product: Name: **ROSCAMAT MOSQUITO** V 300 RPM, V 600 RPM, V 2V 300/600 RPM, VH - 600 RPM, VH - 600 RP, VH - 300 RPM, Model: V 300 RPM, V 600 RPM, V 2 V 300/600 RPM, V E - 600 RPM, VH - 600 RPM, VH - 600 RPM, VH E - 300 RPM, VH 2V - 300/600 RPM, V E - 300 RPM, V E - 600 RPM, 2V E - 300/600 RPM, VH 2V E - 300/600 RPM, V 300 RPM - 120V, V 600 RPM - 120V, V 2V 300/600 RPM - 120 V, VH - 600 RPM - 120V, VH - 600 RPM - 120V, VH - 300 RPM - 120 V, VH 2V - 300/600 RPM - 120 V, V E - 300 RPM - 120V, V E - 600 RPM - 120 V, 2V E - 300/600 RPM - 120 V, VH E - 300 RPM - 120V, VH E - 600 RPM - 120 V. Initial series number: 003-318 (consecutive) Conforms with Directive 2006/42/EC on machinery, Directive 2014/35/EU on electrical equipment designed for use within certain voltage limits (low voltage), Directive 2011/65/EU on restriction of the use of certain hazardous substances in electrical and electronic equipment and Directive 2014/30/EU certified by the TELPRO CE laboratory, Av. Ca n'Enric, 39, 08197 Sant Cugat (Valldoreix), Barcelona Authorised for documentation: Ramon Jou Parrot, TECNOESPIRO MACHINE TOOL, S.L.U.

Sant Joan de Vilatorrada, Friday, 16 February 2024

Ramon Jou Parrot, Chief Engineering Officer





ICNOSP2

APPENDIX ROSCAMAT®

ROSCAMAT ANNEX

1	TA	APPING ACCESSORIES	
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1 <u>TAPPING ACCESSORIES</u>

_ <u>.,</u>	0.1				I
QUICK-(CHANGE TO	DOL HOL	DER		STOCK HOLDER
clutch, attachin	range of tap as well as g different sinking bi s, etc.	s other t tools, su	ools fo uch as	or quickly drill bits,	For threading with stocks Capacity M5–M27
•Tan ho	lder with sa	afoty clut	ch		LONG STOCK HOLDER
	re it slips wh			bottom of	For stock-guided threads. Types:
•Tap ho	<u>lder withou</u>	ut safety (clutch		– Long stock holder 19/1 M5–M6
(to atta	ch differen and drive)			cylindrical	 Long stock holder 19/1 M8 Long stock holder 19/1 M10
	Ø19 mm: c , 550, 750, 1				– Long stock holder 19/1 M12-M14 – Long stock holder 31/2 M16-M18– M20
Type 2 –	Ø31 mm: c	apacity M	14–M3	0	
	170 module				Please enquire about other measurements
Туре 3 –	Ø 48 mm: d	capacity M	130–M4	12	Capacities from M6–M27
(for the	40 modules	5)			QUICK-CHANGE EXTENSION
	STANDARE) MEASUR	REMENT	rs	80-mm extension for head assembly tool, allowing access to hard-to-reach areas. Ø coupling = Ø19 mm
Metric	Ø Coupl.	Ø Shaft		Standard	
M3	19	3.5	2.7	DIN 371	REDUCER BUSHING
M4	19	4.5	3.4	DIN 371	
M5	19	6	4.9	DIN 371	To adapt different coupling
M6	19	6	4.9	DIN 376	diameters of tap holders to
M7	19	7	5.5	DIN 376	modules with different output
M8	19	8	6.2	DIN 376	dimensions.
M10 M12	19 19	10 9	8 7	DIN 376 DIN 376	
M14	19/31	9	9	DIN 376	PROBES
M14	19/31	12	9	DIN 376	Two models available (19 and 31). Angled
M18	31	14	11	DIN 376	threading tools.
M20	31	16	12	DIN 376	
M22	31	18	14.5	DIN 376	
M24	31	18	14.5	DIN 376	
M27	31	20	16	DIN 376	
M30	31/48	22	18	DIN 376	
M33	48	25	20	DIN 376	4
M36	48	28	22	DIN 376	4
M39 M42	48 48	32 32	24 24	DIN 376 DIN 376	

2 MODULAR SYSTEM

2.1 <u>TIGER AND DRAGON MODULES</u>

MODULE	Max. speed (rpm)	Max. torque		Ø Adaptor	Tapping capacity – steel <90 kg	
		Nm	Ft · Ib	·	Metric	Inches
90	90	150	110	Ø31	M16-M27	$\frac{5}{8}$ " - 1 $\frac{1}{8}$ "
170	170	79	58	Ø31	M16-M20	$\frac{5}{8}$ " - $\frac{3}{4}$ "
300	300	44	32	Ø19	M2-M16	1/8" - 5/8"
550	550	24	15	Ø19	M2-M12	$\frac{1}{8}$ " - $\frac{1}{2}$ "
750	750	17	13	Ø19	M2-M10	$\frac{1}{8}$ " - $\frac{3}{8}$ "
1050	1050	12.5	9	Ø19	M2-M8	1/8" - 3/8"
2100	2100	6	4	B-16 cone	•	Ø8 aluminium, ron, etc.

2.2 SHARK MODULES

MODULE	Max. speed	Max. speed Max. torque		Ø Adaptor	Tapping capacity – steel <90 kg	
	(rpm)	Nm	Ft · Ib	•	Metric	Inches
40	40	340	251	Ø48/3	M27-M36	$1 \frac{1}{8} - \frac{1^{3}}{8}$
75	75	185	136	Ø31/2	M18-M27	3/4" - 1 $1/8$ "
140	140	95	70	Ø31/2	M18-M22	$^{3}/_{4}$ " - $^{7}/_{8}$ "
320	320	44	32	Ø19/1	M2-M16	$\frac{1}{8}$ " - $\frac{5}{8}$ "
500	500	28	21	Ø19/1	M2-M12	$\frac{1}{8}$ " - $\frac{1}{2}$ "
900	900	15	11	Ø19/1	M2-M8	1/8" - $3/8$ "

3 <u>ACCESSORIES</u>

NOT all the accessories shown below are compatible with your arm, for this see the compatibility table *[See ROSCAMAT COMPATIBILITY TABLE p. 54]*

	TABLES		
(1)	(2)	(3)	
Fo	ur wheels (two with brake)	*	
Slo	ots for fastening parts or tools.		
	pports for tap holder or tools.		
CODE DESCRIPTION	DIMENSIC		MAX. LOAD
TP0001A0 Small table (1) TF0001A0 Mid-size table (2)		" x 19 11/16" x 35 7/16" x 33 7/16" x 33 7/16"	100 kg 200 kg
907B00A0 Large table (3)		x 33 7/16″ x 33 7/16″	500 kg
	SUPPORTS		
(1) Magr and s (1) CO BR000 BR100	0100 Small clamp (1) 0100 Large clamp (2)	DIMENSIONS N/A N/A	(3)
(2) IA000 IB000 IC000	0100 Magnetic support (4)	150x150 Ø200 Ø250	(4)(5)

		TROLLEY		
	nove the work unit.			
	DESCRIPTION		DIMENSIONS	
	ey 700	700x700 mn		
	ey 900	900x900 mn		
	trical trolley	900x900 mn	-	
	trical trolley	800x800 mn	ון אווע אי	12
COU	0	FIXED COLUN	1N	
	CL144000 Colu CL115800 Colu CL128900 Colu CL140800 Colu CL115400 Colu CL145300 Colu CL145300 Colu CL145300 Colu CL007004 Colu CL05300 Colu CL145800 Colu CL145800 Colu CL145700 Colu CL145800 Colu		2 ½ " 4 3/8" 6 3/8" 10 7/8" 14 ¾" 17 ¾" 25" 29 1/8" 33 ½" 43 ¼" 53 1/8" 63"	
	consists of a tel /linder with anti-ro DESCRIPTION Pneumatic lifter 3 Pneumatic lifter 5 Pneumatic lifter 7	tation.	nn and a pneuma ERTICAL STROKE 300 mm – 11 7/8″ 500 mm – 19 7/8″ 50 mm – 29 17/32″	

D63 PNEUMATIC LIFTER

Pneumatic lift. The vertical position can be locked at any point, it has a pneumatic cylinder. It can be secured to the ground, on a trolley or on the ground rail to have movement on two shafts.

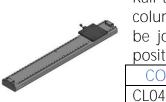
DESCRIPTION	VERTICAL STROKE
1500 D63 Pneumatic lifter	940 mm - 37 ″
2000 D63 Pneumatic lifter	1440 mm – 56 11/16"
2500 D63 Pneumatic lifter	1940 mm – 76 3/8 "

RADIAL EXTENSION

Extender that enables the arm's working area to be increased. It can also be installed on other accessories, such as column, lift, linear guide, etc.

CODE	DESCRIPTION	ADDITIONAL WORK AREA
ER0010C0	Radial extension 500 (1)	500 mm – 19 11/16 "
ER000100	Radial extension 1000 (2)	1000 mm - 39 3/8 "

FLOOR RAIL



(1)

Rail to fasten to the floor and on which the different columns and lifts can be fastened. Several sections can be joined from a base section 2 m. The horizontal position can be locked at any point.

CODE	DESCRIPTION	STROKE
L040000	Floor rail	1520 mm – 59 13/16 "

LINEAR GUIDE

Guide for the horizontal movement of the arm. Several sections can be joined from a base section 2 m. This may be table-top, fixed to the wall or ceiling, or on pillars of various heights that can be selected. The horizontal position can be locked at any point.

CODE	DESCRIPTION	STROKE
CL023300	Linear guide 1000	635 mm – 25 "
CL020000	Linear guide 2000	1635 mm - 64 3/8 "
CL023000	Linear guide 3000	2635 mm – 103 3/4 "

(2)

4 ROSCAMAT COMPATIBILITY TABLE

ACCESSORY	SERIES – ROSCAMAT						
	200	400	500	Mosquito	Tiger	Shark	Dragon
RADIAL EXTENSION	•		•	•	•	•	•
TROLLEY + FIXED COLUMN			•	□700x18	□700x24	□700x30	□700x36
FIXED COLUMN		•	•	•	•	•	•
PNEUMATIC LIFTER		•	•	•	•	•	•
D63 PNEUMATIC LIFTER			•	•	•	•	•
FLOOR RAIL		•	•	•	•	•	•
LINEAR GUIDE	•		0	•	0	0	0
SMALL TABLE (500)			Ø	•	0	0	0
MID-SIZE TABLE (850 x 850)		•	•		•	*	*
LARGE TABLE (1110 x 850)		•	•	•	•	•	•
SMALL CLAMP	•		0	•	0	0	0
LARGE CLAMP					•		
MAGNETIC SUPPORT	□150	Ø200	Ø250	Ø200	Ø250	Ø250	Ø250

= Compatible = NOT Compatible \otimes

= Request information *

5 TECHNICAL INFORMATION

5.1 MOTOR – PROPERTIES

High frequency electric motor Three models with different speeds:

- a) 300 rpm
- b) 600 rpm
- c) Two-speed: 300/600 rpm
- Power: 450 W.
- Frequency: 50/60 Hz
- Single phase; Voltage: 220–240 V.
- Machine weight: 15 kg.
- Noise level: 74 dBA



5.2 <u>ELECTRONIC VARIATOR PROPERTIES</u>

5.2.1 <u>Variable frequency drive (used in 230V versions)</u>

Nominal dimensions		I dimensions	Technical Specifications	
Nom	Nominal power of motor		0.4 kW	
es	Nominal power (kVA)		1.3 kVA	
erti	Nominal voltage (V)		Three-phase, 200 to 240V (with AVR function)	
odo	Nominal curr	ent	3.5 A.	
pr	Overload cap	acity	150% of nominal output current for 1 min.	
out	Overload cap	Jacity	200% of nominal output current for 0.5 sec.	
Output properties	Nominal frequency (Hz)		50 / 60 Hz	
S	Phases, voltage, frequency		Single phase, 200 to 240 V 50/60 Hz	
rtie	Tolerances		Voltage: +10 to -15%	
bei	TOIETATICES		Frequency: +5% to -5%	
oro	Nominal	(With DC reactance)	3.5 A.	
ut p	current	(Without DC reactance)	5.4 A.	
Input properties	Power required from the electricity supply (kVA)		0.7 kVA	
	Brake torque (%)		100 (average brake torque with AVR off)	
es			Start frequency: 0.0–60.0 Hz	
Brakes	DC brake injection		Braking time: 0.0–30.0 secs	
B			Brake current: 0–100% of nominal current	
	Braking transistor		Built-in	
	Applicable safety standards		UL508C, IEC61800-5-1:2007	
Prote	Protection type		IP20 (IEC 60529), UL open type (UL50)	
Cool			Natural cooling	
Weig	ht		0.7 kg	

5.2.2 <u>Variable frequency drive (used in 120V versions)</u>

Nominal dimensions		I dimensions	Technical Specifications		
Nom	Nominal power of motor		0.4 kW		
es	Nominal power (kVA)		0.95 kVA		
erti	Nominal voltage (V)		Three-phase, 200 to 240V (with AVR function)		
obe	Nominal curr	ent	2.5 A.		
pr	Overload cap	acity	150% of nominal output current for 1 min.		
out	Overioau cap	bacity	200% of nominal output current for 0.5 sec.		
Output properties	Nominal frequency (Hz)		50 / 60 Hz		
S	Phases, voltage, frequency		Single phase, 100 to 120 V 50/60 Hz		
rtie	Tolerances		Voltage: +10 to -10%		
bei			Frequency: +5% to -5%		
oro	Nominal	(With DC reactance)	6.4 A.		
ut p	current	(Without DC reactance)	9.5 A.		
Input properties	Power required from the electricity supply (kVA)		0.7 kVA		
	Brake torque	(%)	100 (average brake torque with AVR off)		
Brakes	DC brake injection		Start frequency: 0.0–60.0 Hz		
ak			Braking time: 0.0–30.0 secs		
B			Brake current: 0–100% of nominal current		
	Braking transistor		Built-in		
	Applicable safety standards		UL508C, IEC61800-5-1:2007		
	Protection type		IP20 (IEC 60529), UL open type (UL50)		
	Cooling		Fan		
Weig	ht		0.8 kg		

5.3 TABLE OF TORQUE – THREAD SIZE – MOSQUITO

TORQUE	SIZE	WHITWORTH	GAS	STEEL > 80	STEEL < 80 CAST BRONZE < 40	ALUMINIU M PLASTIC
0.3 0.5 0.6 0.8	M2 M3	1/8"		600 RPM	600 RPM	
1 1.2 1.6	M4	5/32"				
2 2.5	M5					
3 4 5	M6	3/16" 7/32" 1/4"				600 RPM
6			G 1/8"			
8	M8					
10		5/16"				
12 16	M10	3/8"				
18 20			G 1/4"	300 RPM	300 RPM	
22	M12	7/16"	G 3/8"			
25						
28						
32 36	M14	1/2"				300 RPM
40	M14	9/16"				

5.4 CLUTCH TORQUE ADJUSTMENTS FOR TAPPING (Nm)

Metric thread	Steel > 100 kg	Steel 80–100 kg	Steel < 80 kg	Aluminium Grey Iron
3	0.9	0.6	0.5	0.4
4	2	1.3	1.2	0.8
5	3	2	2	1.3
6	5	4	4	2.4
8	11	8	8	5
10	20	15	14	9
12	33	24	23	14
14	50	36	35	22
16	57	42	40	26
18	101	73	70	45
20	112	81	78	50
22	123	90	86	55
24	194	140	135	86
27	218	158	152	97
30	330	240	230	150
33	364	260	252	160
36	-	-	280	230
39	-	-	_	250
42	-	-	-	340

5.5 MACHINE THREAD TAPS

Blind hole	Tap with helical grooves.			
Lubrication	Tap with straight grooves and helical entry.	Lubrication.		
Steel > 80 kg	Ang. cutting 8–10.	Cutting additives.	fluid	with
Steel < 80 kg	Ang. cutting 12–14.			
Steel < 50 kg Stainless steel	Ang. cutting 14–16. Treatment of surface	Cutting fluid		
Soft iron casting	Tap with straight grooves. Treatment of Nitride Surface Ang. cutting 5.	Petroleum, dry	cutting	fluid,
Duralumin	Ang. cutting 12–15.	Cutting fluid	, dry	
Aluminium	Ang. cutting 17–25.	Cutting additives.	fluid	with
Plastic		Cutting fluid	, dry	